

Explainable AI for Science

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Al helps in many Research Areas

A (very rough) spectrum of research discipline system

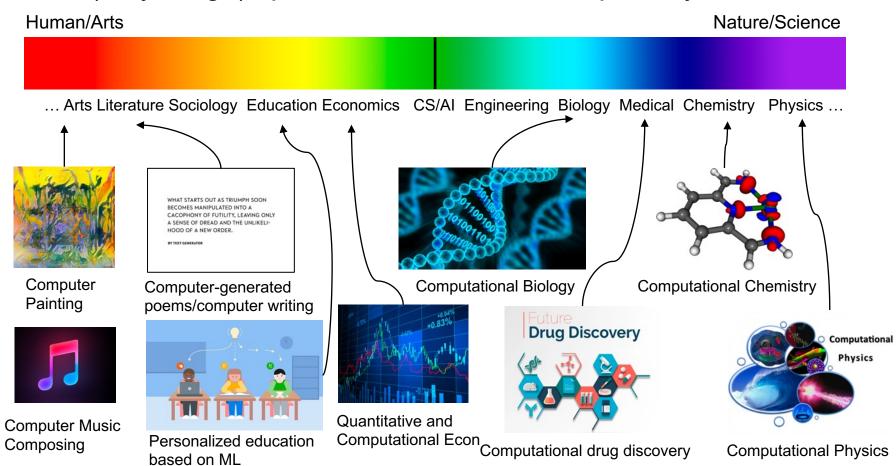
Human/Arts Nature/Science

... Arts Literature Sociology Education Economics CS/AI Engineering Biology Medical Chemistry Physics ...



Al helps in many Research Areas

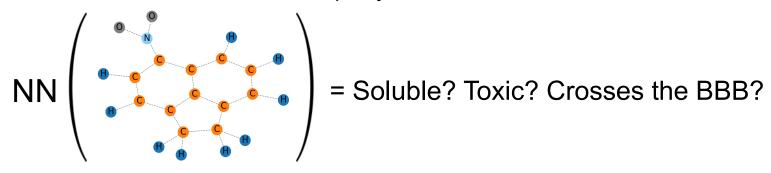
A (very rough) spectrum of research discipline system





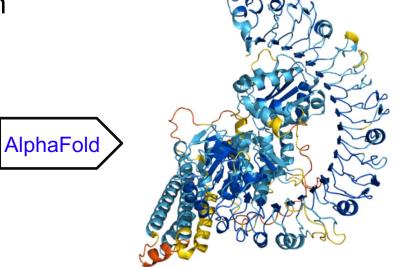
Al for Science: Some Examples

- Al for Drug Discovery
 - Molecule Generation and Property Prediction



Protein Structure Prediction

MAGELVSFAVNKLWDLLSHEYTLFQGVEDQVAELKSDLNL
LKSFLKDADAKKHTSALVRYCVEEIKDIVYDAEDVLETFV
QKEKLGTTSGIRKHIKRLTCIVPDRREIALYIGHVSKRIT
RVIRDMQSFGVQQMIVDDYMHPLRNREREIRRTFPKDNES
GFVALEENVKKLVGYFVEEDNYQVVSITGMGGLGKTTLAR
QVFNHDMVTKKFDKLAWVSVSQDFTLKNVWQNILGDLKPK
EEETKEEEKKILEMTEYTLQRELYQLLEMSKSLIVLDDIW
KKEDWEVIKPIFPPTKGWKLLLTSRNESIVAPTNTKYFNF
KPECLKTDDSWKLFQRIAFPINDASEFEIDEEMEKLGEKM
IEHCGGLPLAIKVLGGMLAEKYTSHDWRRLSENIGSHLVG
GRTNFNDDNNNSCNYVLSLSFEELPSYLKHCFLYLAHFPE
DYEIKVENLSYYWAAEEIFQPRHYDGEIIRDVGDVYIEEL
VRRNMVISERDVKTSRFETCHLHDMMREVCLLKAKEENFL
QITSNPPSTANFQSTVTSRRLVYQYPTTLHVEKDINNPKL





The Explainability Crisis

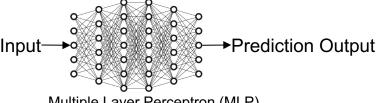
- A Key Problem with current AI models
 - Most Al prediction methods are not explainable
 - They can make good predictions based on massive data and complicated models, but are less capable of explaining the prediction results and reveal the insights to human scientists
 - They can produce prediction results, but hardly explains why the results are predicted they way they are
- Origin of the Problem
 - Difference from traditional methods: Whitebox vs. Blackbox models



e.g., (partial) differentiable equation

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{\nabla P}{\rho} + \nu \nabla^2 \mathbf{u},$$

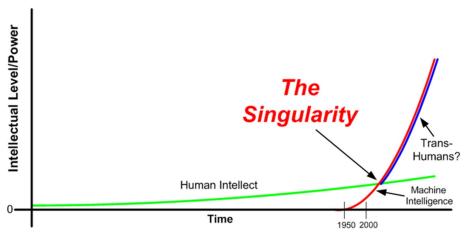
e.g., deep neural networks





Why Explainable AI for Science?

- The essence of scientific research is to understand the "why"
 - Not only know how but also know why
 - Know how: Blackbox AI for Prediction; Know why: Explainable AI for Explanation
 - In many cases, understanding the "why" behind the result is even more important than just knowing the result itself, because knowing the why implies real growth of knowledge and helps in making critical decisions
 - Furthermore, if AI accumulates more and more dark knowledge that are not understandable to humans (which is already happening), it may eventually lead to a singularity where humans are lagged behind on the conquest of knowledge than machines





The Conquest of "Why" in Science

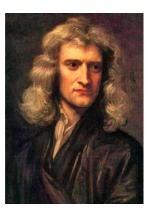
- The conquest of why has always been the key theme of science in human history
- A Legend Example
 - The Kepler's Laws of Planetary Motion
 - The Newton's Law of Universal Gravitation











Tycho Brahe (1546-1610)

Johannes Kepler (1571-1630)

Isaac Newton (1643-1727)

Kepler's Laws of Planetary Motion



We can
Obverse it!



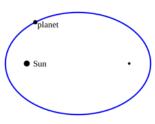
We can Predict it!

Tycho Brahe (1546-1610) Demark astronomer

Good at astro-observation

Observed and recorded a lot of data about Mars movement.

Time	Position
1	(a,b)
2	(c,d)
3	(e,f)



Johannes Kepler (1571-1630) German astronomer, student of Tycho Brahe.

Analyzed Tycho's data, and discovered the rules hidden in the data.

The "Kepler's laws of planetary motion":

$$\frac{r^3}{T^2} = K$$

T: period of circling around the sun, r: radius

Time	Position	2	
1	(a,b)	$\frac{r^3}{-}=K$	p b
2	(c,d)	$\overline{T^2} = K$	rmax
3	(e,f)		Y

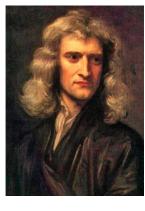


Is the Story Over? No!



We can **Predict** it!





We **Understand** it! We know Why!

Johannes Kepler (1571-1630) German astronomer, student of Tycho Brahe.

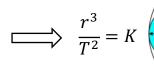
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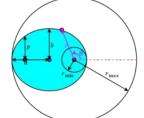
The "Kepler's laws of planetary motion": $\frac{r^3}{T^2} = K$

$$\frac{r^3}{T^2} = K$$

 τ : period of circling around the sun, r: radius

Time	Position
1	(a,b)
2	(c,d)
3	(e,f)





Isaac Newton (1643-1727) English mathematician, physicist, astronomer, theologian, and author.

Proposed the Newton's law of universal gravitation + differential calculus:

Naturally derives out the Kepler's laws of planetary motion!

$$rac{r^3}{T^2} = K$$
 is because $F = G rac{m_1 m_2}{r^2}$



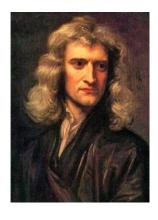
Three Key Roles in the Scientific Discovery Process











Tycho Brahe (1546-1610)

Johannes Kepler (1571-1630)

Isaac Newton (1643-1727)

Observation

Time	Position
1	(a,b)
2	(c,d)
3	(e,f)

Analyzation

$$\frac{r^3}{T^2} = K$$

Explanation

$$F=Grac{m_1m_2}{r^2}$$

What if Kepler had DL in the 16-17th Century?



We can Obverse it!





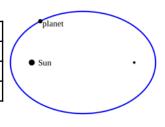
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Position
(a,b)
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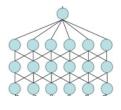


Johannes Kepler (1571-1630) German astronomer, student of Tycho Brahe.



There could be some rules underlying the data. I don't know what it is, but NN can fit any function. So I'm going to train a NN to fit the data!





It fits the data pretty well! I can make predictions! $r = some\ NN(T)$

But wait: can this be called scientific discovery? Science is not only about know HOW, but also know WHY!



Challenges in Modern Scientific Research



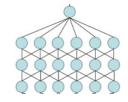
We can Predict it!

Johannes Kepler (1571-1630) German astronomer, student of Tycho Brahe.



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- However, manually analyzing data as Kepler did is very challenging in modern scientific research
 - Since the amount of data is huge
 - e.g., produced by astronomical telescope and particle colliders
- We indeed need Al for data analyses and model learning

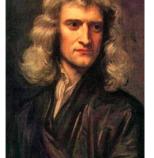


Challenges in Modern Scientific Research



We can **Predict** it!





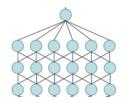
We **Understand** it! We know **Why**!

Johannes Kepler (1571-1630)
German astronomer, student of Tycho Brahe.



There could be some rules underlying the data. I don't know what it is, but NN can fit any function. So I'm going to train a NN to fit the data!





It fits the data pretty well! I can make predictions! $r = some\ NN(T)$ Isaac Newton (1643-1727)

Explainable AI (XAI) plays the role of Newton

Interpret and **explain** the learned (black-box) model, reveal its insights to human scientists

Help us better understand the nature.



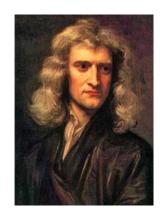
Three Key Roles in the Scientific Discovery Process Using more CS/AI language











Tycho Brahe (1546-1610)

Johannes Kepler (1571-1630)

Isaac Newton (1643-1727)

Observation

Analyzation

Explanation

Data Collection

Model Learning

Model Interpretation (XAI)

$$\frac{\tau^2}{r^3} = K$$

$$F=Grac{m_1m_2}{r^2}$$

Almost automated

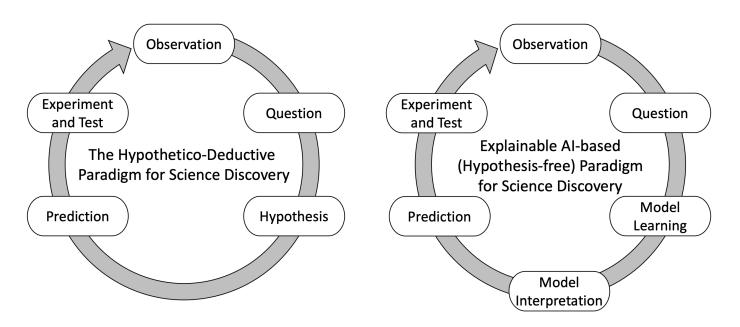
Many available methods

Still needs much exploration



A Paradigm Shift (again) for Scientific Research

- From Theory-driven to Data-driven (back to Kepler), but with Explainable AI (plus Newton)
 - Blackbox AI for Prediction (the Kepler model)
 - Explainable AI for Explanation (the Newton model)
- A Paradigm Shift in Scientific Discovery
 - Explainable AI replaces manual hypothesis generation





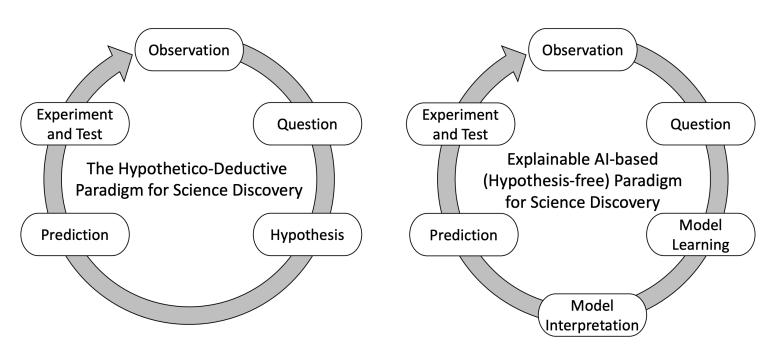
Three Examples on Explainable AI for Science

- Rediscover Kepler's laws and Newton's laws from Tycho's ancient data [1]
 - A good example to demonstrate the idea of XAI-driven scientific research
 - Pay our respect to some of the greatest minds in human history
- More "practical" Examples
 - Explainable AI for Molecular Property Prediction [2]
 - Explainable AI for Biodiversity Conservation [3]
- [1] Zelong Li, Jianchao Ji, and Yongfeng Zhang. "From Kepler to Newton: Explainable AI for Science Discovery." In ICML AI for Science 2022.
- [2] Juntao Tan, Shijie Geng, Zuohui Fu, Yingqiang Ge, Shuyuan Xu, Yunqi Li, and Yongfeng Zhang. "Learning and evaluating graph neural network explanations based on counterfactual and factual reasoning." In Proceedings of the ACM Web Conference 2022.
- [3] Meet Mukadam, Mandhara Jayaram, and Yongfeng Zhang. "A Representation Learning Approach to Animal Biodiversity Conservation." In Proceedings of the 28th International Conference on Computational Linguistics. 2020.



From Kepler to Newton: A Case Study

- A New Paradigm for Scientific Discovery
 - Model Learning and Interpretation automatically generates hypothesis
- Use the paradigm to rediscover:
 - Kepler's Laws of Planetary Motion
 - Newton's Law of Universal Gravitation



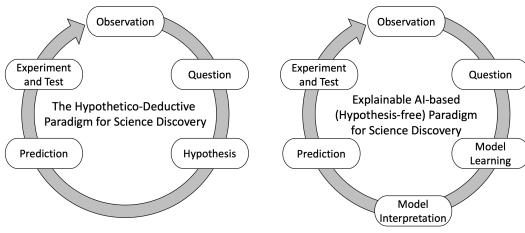


Kepler's Reasoning Process

- At Kepler's time, there were three models of planetary motion
 - The Ptolemaic, Copernican and Tychonic systems
 - Kepler mentioned that these three systems all had high prediction accuracy in the near term, but diverged and failed to fit historical and future observations in the long term
 - Propose a new hypothesis: the orbit of a planet is an ellipse with the Sun at one of the two foci (Kepler's first law of planetary motion)
 - Then he used the observation data to test his hypothesis

 We show the hypothesis-free scientific discovery process based on Explainable AI

 We directly start from data to rediscover the Kepler's laws.





Dataset: Ancient Mars Data from Tycho Brahe

Time	Mars' Position	Sun-Mars	Difference
YYYY/MM/DD	in Ecliptic	Distance	
1582/11/23 16:00	90.70306°	1.58852	+1'30"
1582/12/26 08:30	106.12167°	1.62104	+3'49''
1582/12/30 08:10	107.94222°	1.62443	+5'50''
1583/01/26 06:15	120.10667°	1.64421	-2'33''
1584/12/21 14:00	123.86250°	1.64907	+1'04"
1585/01/24 09:00	138.78556°	1.66210	-3'32''
1585/02/04 06:40	143.56139°	1.66400	-3'08''
1585/03/12 10:30	159.38722°	1.66170	-2'29''
1587/01/25 17:00	158.22778°	1.66232	-0'10''
1587/03/04 13:24	174.94722°	1.64737	-0'59''
1587/03/10 11:30	177.59833°	1.64382	0'0''
1587/04/21 09:30	196.74750°	1.61027	+1'30''
1589/05/08 16:24	196.92056°	1.61000	-2'43''
1589/04/13 11:15	214.03056°	1.57141	+1'40''
1589/04/15 12:05	215.02806°	1.56900	+0'37''
1589/05/06 11:20	225.51000°	1.54326	+0'57''
1591/05/13 14:00	252.12722°	1.47891	-4'24''
1591/06/06 12:20	265.64667°	1.44981	-3'15''
1591/06/10 11:50	267.94694°	1.44526	-4'39''
1591/06/28 10:24	278.49222°	1.42608	-5'39''
1593/07/21 14:00	320.02722°	1.38376	-2'31''
1593/08/22 12:20	340.25694°	1.38463	-0'36''
1593/08/29 10:20	344.62083°	1.38682	-2'19''
1593/10/03 08:00	6.32750°	1.40697	-0'16''
1595/09/17 16:45	22.82194°	1.43222	-1'27''
1595/10/27 12:20	45.59389°	1.47890	-0'29''
1595/11/03 12:00	49.44250°	1.48773	+0'03''
1595/12/18 08:00	73.04139°	1.54539	-0'59''

Table 1: Position of Mars when orbiting the Sun

Data copied from Kepler's book
 Astronomia Nova (1609)

Three main variables

Time: t

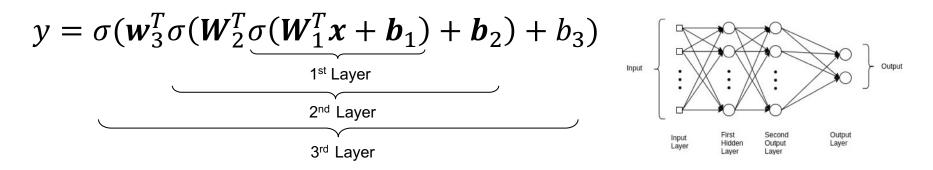
- Mars angular position: θ

Sun-Mars distance: r



Blackbox and Whitebox Models

- The black-box model for Prediction and Data Augmentation
 - Simple Multiple Layer Perceptron (MLP) neural network



- The white-box model for Explanation
 - Symbolic Regression: Transform the MLP neural network into a symbolic equation



Rediscover Kepler's Laws based on Explainable Al

Black-box Model (DNN) for Prediction and Data Augmentation

$$r = NN(\theta)$$

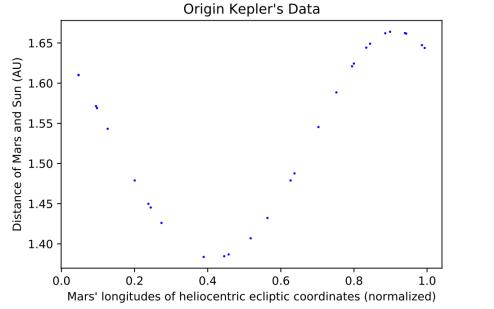


Figure 3: Data Visualization before Training

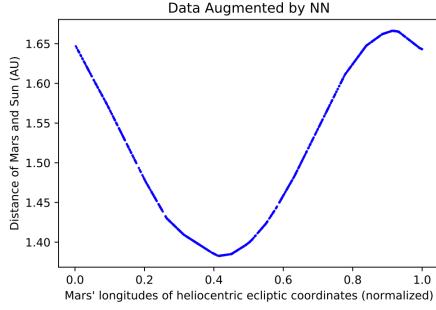


Figure 4: Data Visualization after Training

Use 90% data points for training and 10% for validation. MSE on training data: 4×10^{-11} ; MSE on validation data: 7×10^{-8} Blackbox neural networks can already make accurate predictions, though we don't understand the insight



Rediscover Kepler's Laws based on Explainable Al

- White-box Model for Explanation
 - Symbolic regression based on the augmented data

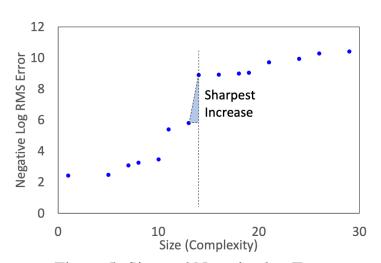


Figure 5: Size and Negative log Error

Size	Error	Function
1	0.088419	1.54806
5	0.084370	$1.54329 + 0.0130577 \cdot \theta$
7	0.045791	$1.45537 + 0.021878 \cdot heta \cdot heta$
8	0.038594	$1.53256 - 0.101048 \cdot \cos \theta$
10	0.031201	$1.65411 - \frac{0.321963}{1.21921 + \theta \cdot \theta}$
11	0.004519	$1.51578 - 0.142019 \cdot \cos{(\theta + 0.542453)}$
13	0.003003	$1.51836 - 0.141285 \cdot \cos(0.979081 \cdot (-0.544189 - \theta))$
14	0.000136	$\frac{1.51977}{1.00625 + 0.0932972 \cdot \cos(\theta + 0.544536)}$
16	0.000133	1.51 9 75
18	0.000124	$\frac{1.00625 + 0.0933058 \cdot \cos(1.00017 \cdot \theta + 0.544619)}{1.5221}$
19	0.000118	$\frac{1.0078 + \sin(0.0935495 \cdot \cos(\theta + 0.544689))}{1.51016 - \frac{0.0794197}{0.0536393 + \frac{0.567314}{\cos(1.00052 \cdot (0.544488 + \theta))}}}{1.51978}$
0.1	0.000000	$\frac{0.0536393 + \frac{0.001514}{\cos(1.00052 \cdot (0.544488 + \theta))}}{1.51978}$
21	0.000060	$\frac{1.00625 + 0.0932649 \cdot \cos(\theta + 0.544414 + \frac{0.000322752}{\theta - 1.48167})}{1.00625 + 0.0932649 \cdot \cos(\theta + 0.544414 + \frac{0.000322752}{\theta - 1.48167})}$
24	0.000048	$1.51031 - \frac{0.0793261}{0.0507164} - \frac{0.0793261}{0.56737}$
26	0.000024	$1.51031 - \frac{\frac{0.052716 + \frac{0.56737}{\cos(0.543701 + \theta)} - \frac{0.000771507}{1.48757 - \theta}}{0.0793521} \\ 1.51023 - \frac{\frac{0.0531939 + \frac{0.56753}{\cos(0.543898 + 1.00028 \cdot \theta)} - \frac{0.00067777}{1.49235 - \theta}}{\cos(-0.543588 - \theta)}$
26	0.000034	$1.51023 - \frac{0.56753}{0.0531939 + \frac{0.56753}{\cos(0.543898 + 1.00028 \cdot \theta)} - \frac{0.00067777}{1.49235 - \theta}}$
29	0.000030	$1.51032 - \frac{\cos(-0.543588 - \theta)}{7.14742 + 0.662010}$
	3.33333	$1.91032 - \frac{1.91032}{7.14743 + 0.668919 \cdot \cos(0.55992 - \frac{0.00769976}{1.58368 - \theta} + \theta)}$

Table 2: Symbolic Regression Results

$$r = f(\theta) = \frac{1.51977}{1.00625 + 0.0932972 \cdot \cos(\theta + 0.544536)} = \frac{1.51033}{1 + 0.0927177 \cdot \cos(\theta + 0.544536)}$$
 22



Rediscover Kepler's Laws based on Explainable Al

- Physical Interpretation of the Results
 - Mars orbit is an ellipse, and Al-derived eccentricity is 0.0927177
 - Very close to Kepler's result 0.09264 (relative error < 0.1%) and modern result 0.09341233 (relative error < 0.7%)

$$r = f(\theta) = \frac{1.51977}{1.00625 + 0.0932972 \cdot \cos(\theta + 0.544536)} = \frac{1.51033}{1 + 0.0927177 \cdot \cos(\theta + 0.544536)}$$

- $r_{min} = f[\theta = -0.544536 (-31.2^{\circ})]$, indicating closest Mars Opposition in August, which is consistent with historical observations
 - 31.2/360 × 365 ≈ 32 days ahead of the fall equinox, thus in August

Year (AD)	Date	Earth-Mars Distance in AU
1561	Aug. 07	0.37325
1640	Aug. 20	0.37347
1687	Aug. 09	0.37434
1719	Aug. 25	0.37401
1766	Aug. 13	0.37326
1845	Aug. 18	0.37302
1924	Aug. 22	0.37285
2003	Aug. 27	0.37272
2050	Aug. 15	0.37405

Table 5: Closest Approaches of Mars Oppositions in History



- Black-box Model for Prediction and Data Augmentation
- We already have $r = f(\theta)$, we want $\theta = g(t)$
 - So we can predict the position of Mars (θ, r) for any given time t

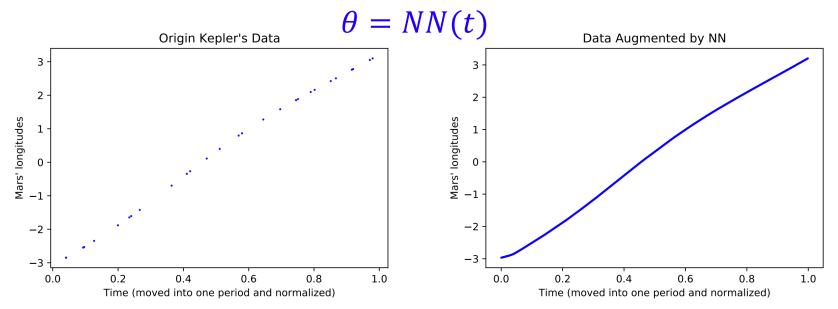


Figure 6: Data Visualization before Training

Figure 7: Data Visualization after Training

Use 90% data points for training and 10% for validation.

MSE on training data: 7×10^{-8} ; MSE on validation data: 1.5×10^{-5}

Blackbox neural networks can already make accurate predictions, though we don't understand the insight

- Deep Learning for Prediction and Data Augmentation
 - The simple experiment implies a significant role of machine learning (especially deep learning) in scientific discovery
- The real $t \theta$ relation based on advanced math tools and deeper understandings of planetary motion:

$$\frac{2\pi}{T}t = 2\tan^{-1}\left(\sqrt{\frac{1-\epsilon}{1+\epsilon}}\tan\left(\frac{\theta}{2}\right)\right) - \frac{\epsilon\sqrt{1-\epsilon^2}\sin(\theta)}{1+\epsilon\cos(\theta)}$$

– i.e., we can express t as a function of θ , i.e., $t = h(\theta)$, however, we can hardly find a function to express θ as t, i.e., $\theta = g(t)$, since it is a transcendental equation

- However, we still want some θ -as-t relationship
 - We already have $r = f(\theta)$, if we have $\theta = g(t)$, then we can predict the position of Mars (r, θ) for any time t
- We can adopt deep neural networks to learn a black-box predictor $\theta = NN(t)$
 - Universal Approximation Theorem (UAT) [4,5,6]
 - A network containing a finite number of neurons can approximate arbitrarily well any real-valued continuous functions on compact subsets of Rⁿ.
 - $-\theta = NN(t)$ is differentiable!
 - We can conduct mathematical analysis on the θ -as-t relationship

•
$$\omega = \frac{dNN(t)}{dt}$$
, $a = \frac{d^2NN(t)}{dt^2}$

 Makes it possible to analyze the relationship between many variables that are otherwise difficult to calculate

^[5] Cybenko, G. (1989). Approximations by superpositions of sigmoidal functions. Mathematics of Control, Signals, and Systems, 2(4):303–314.

^[6] Hornik, Kurt (1991). Approximation capabilities of multilayer feedforward networks. Neural networks, 4(2): 251-257.



White-box Model for Explanation

- Variable augmentation $(t_i, \theta_i, r_i, \omega_i)$
- $\theta_i = NN(t_i), r_i = f(\theta_i) = f(NN(t_i)), \omega_i = \frac{NN(t_i + \delta) NN(t_i \delta)}{2\delta}$
- Augment variable without prior assumption: $(t_i, \theta_i, r_i, r_i^2, r_i^3, \omega_i, \omega_i^2, \omega_i^3)$

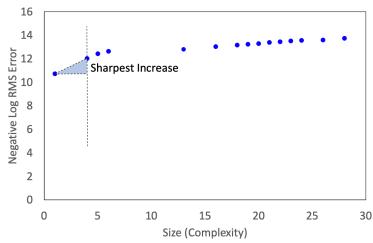


Figure 8: Size and Negative log Error for r and ω

Size	Error	Function
1	0.000022	8.18954×10^{-5}
4	0.000006	$\frac{0.000298491}{r_3}$
5	0.000004	$0.000218591 \cdot (1.92033 - r)$
6	0.000003	$(-2.65592 \times 10^{-3} + \frac{0.000390417}{1})$
13	0.000003	$-8.50685 \times 10^{-5} + \frac{0.000395123}{r_2 - \frac{0.000290053}{r - 1.48997}}$
16	0.000002	0.000100316
22	0.000001	$\frac{-1.08788 - 0.0590273 \cdot \cos(-2147483648 \cdot r_3) + r_2)}{0.000448514} \frac{0.0460772}{(\frac{0.0460772}{r_3 - 3.36628} \cdot \cos(\frac{r_3}{-3.79879 \times 10^{-5}}) + r_3) \cdot r}$

Table 6: Symbolic Regression Result for r and ω

$$\omega^2 = \frac{0.000298491}{m^3}$$
, or $r^3\omega^2 = c = 0.000298491AU^3day^{-2}$



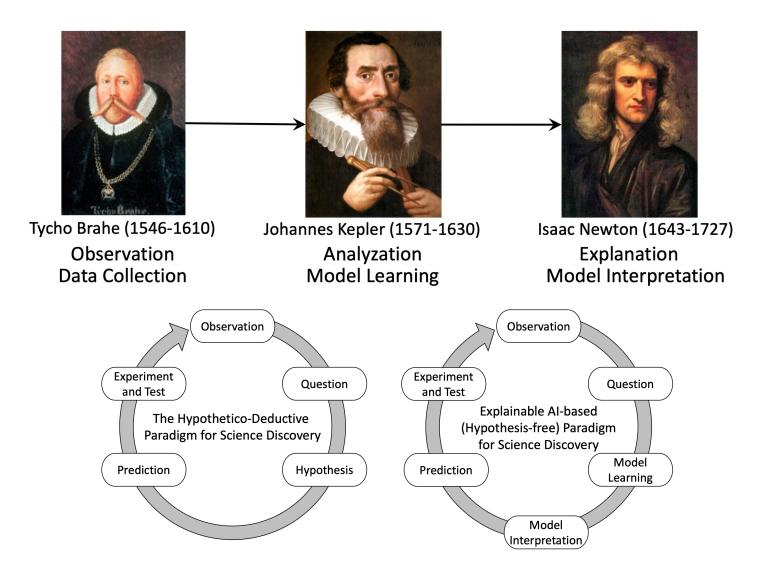
Physical Interpretation of the Results

$$\omega^2 = \frac{0.000298491}{r^3}$$
, or $r^3\omega^2 = c = 0.000298491AU^3day^{-2}$

- $r^3\omega^2$ is close to modern result: $r^3\omega^2 = GM = 2.96 \times 10^{-4} AU^3 day^{-2}$
 - Relative error < 0.8%
- Acceleration $a = r\omega^2 = \frac{0.000298491}{r^2} \propto \frac{1}{r^2}$
- Leading to the inverse-square law of acceleration and gravitation
- Also Kepler's third law
 - $\frac{r^3}{T^2} = \frac{c}{4\pi^2} = 7.56086 \times 10^{-6} AU^3 day^{-2}$
 - Close to Kepler's result $7.5 \times 10^{-6} AU^3 day^{-2}$
 - Relative error < 0.82%



Recap

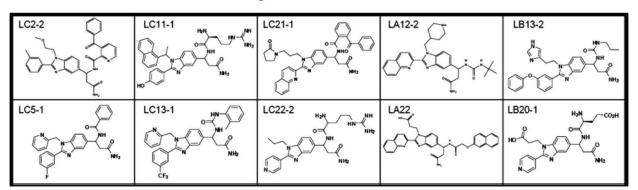




The Molecule Classification Problem

- Predicting the function of molecules
 - A fundamental problem in many chemistry/biological/medical research tasks, e.g., drug discovery
- Mathematically, molecule is a graph
 - Current approaches use Graph Neural Networks (GNN) for prediction
 - E.g., Predict if a molecule is soluble, toxic, or can pass the Blood-Brain Barrier (BBB)
 - A binary classification problem

However, we want to know why the model believes in the classification result



30



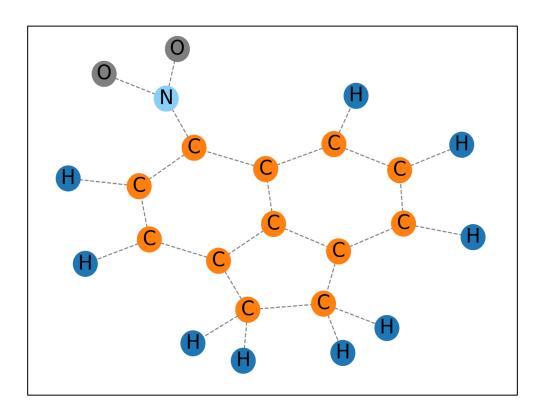
Explainable Graph Neural Networks

Our goal is to develop Explainable Graph Neural Networks (XGNN)

GNN
$$\left(\begin{array}{c} \begin{array}{c} \begin{array}{c} \\ \\ \\ \end{array} \end{array}\right)$$
 = Yes / No $\begin{array}{c} \\ \\ \end{array}$ XGNN $\left(\begin{array}{c} \\ \\ \end{array}\right)$ = Yes / No + Explanation

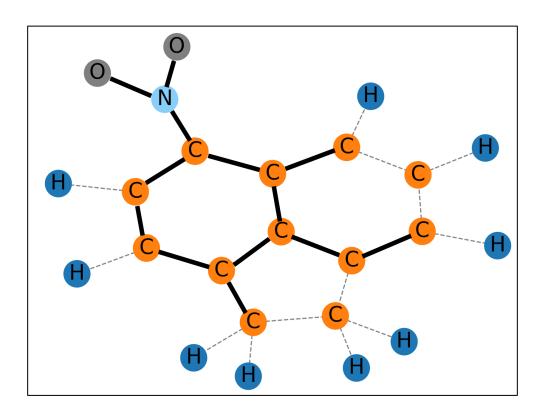


- Example: Molecule mutagenetic prediction
 - If the GNN model predicts the molecule as mutagenetic, why?



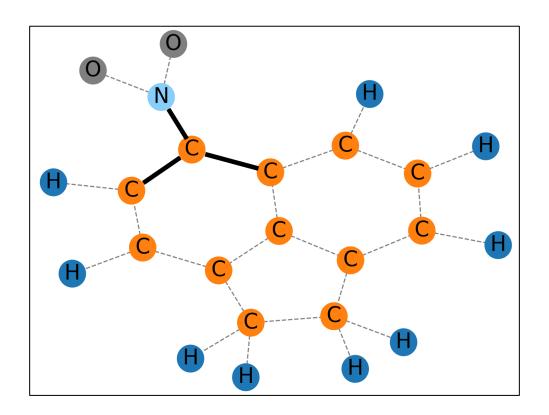


- Factual explanation seeks a sufficient condition
 - The molecule will be mutagenetic with the highlighted bonds



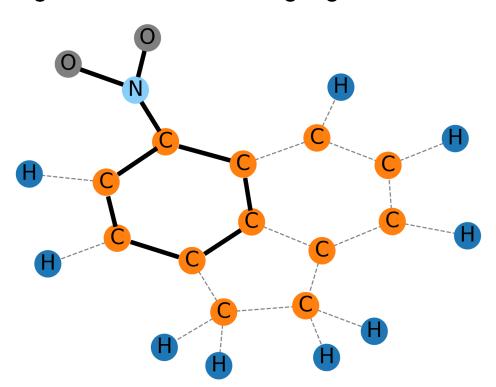


- Counterfactual explanation seeks a necessary condition
 - The molecule will not be mutagenetic without the highlighted bonds





- Factual and Counterfactual explanation seeks a compact (both sufficient and necessary) condition
 - The molecule will be mutagenetic with the highlighted bonds
 - The molecule will not be mutagenetic without the highlighted bonds
 - No more, no less, just OK



How to Find the Explanations?

- A Given graph $G_k = \{\mathcal{V}_k, \mathcal{E}_k\}$. Adjacency matrix $A_k \in \{0,1\}^{|\mathcal{V}_k| \times |\mathcal{V}_k|}$. Node feature matrix $X_k \in \mathbb{R}^{|\mathcal{V}_k| \times d}$.
- The ground-truth class label is $y_k \in C$ (mutagenetic, non-mutagenetic).
- The GNN will predict the estimated label \hat{y}_k for G_k by:

$$\hat{y}_k = \arg\max_{c \in C} P_{\Phi}(c \mid A_k, X_k)$$

- Generate edge mask $M_k \in \{0,1\}^{|\mathcal{V}_k| \times |\mathcal{V}_k|}$, feature mask $F_k \in \{0,1\}^{|\mathcal{V}_k| \times d}$.
- Explanation: Sub-graph $A_k \odot M_k$, sub-features $X_k \odot F_k$.



How to Find the Explanations?

- Factual Reasoning: "Given A already happened, will B happen?".
- Factual Condition:

$$\underset{c \in C}{\operatorname{arg\,max}\, P_{\Phi}(c \mid A_k \odot M_k, X_k \odot F_k) = \hat{y}_k}$$
The remaining edges

- Counterfactual Reasoning: "If A did not happen, will B still happen?"
- Counterfactual Condition:

$$\underset{c \in C}{\operatorname{arg\,max}\, P_{\Phi}(c \mid A_k - A_k \odot M_k, X_k - X_k \odot F_k) \neq \hat{y}_k}$$
The removed edges

What are good Explanations? Simple and Effective

- Occam's Razor Principle
 - If two explanations are equally effective in explaining the results, we prefer the simpler explanation than the complex one.
- To character Simpleness
 - Explanation Complexity

$$C(M,F) = ||M||_0 + ||F||_0$$

How many edges are How many features are included in the explanation

- To character Effectiveness
 - Factual Explanation Strength

$$S_f(M,F) = P_{\Phi}(\hat{y}_k \mid A_k \odot M_k, X_k \odot F_k)$$

Counterfactual Explanation Strength

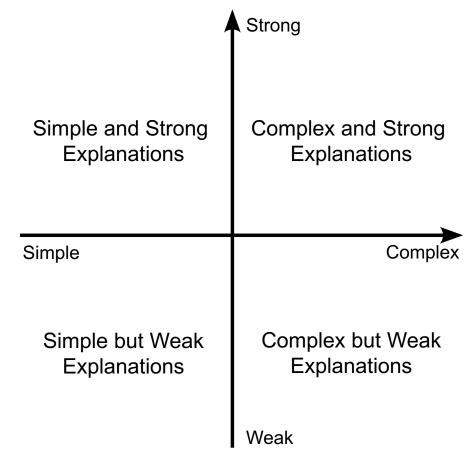
$$S_c(M, F) = -P_{\Phi}(\hat{y}_k \mid A_k - A_k \odot M_k, X_k - X_k \odot F_k)$$

Both should be large enough to satisfy the conditions



Complexity vs. Strength

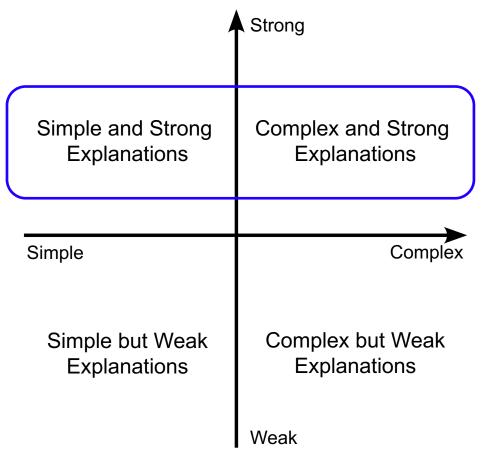
Two orthogonal concepts





Complexity vs. Strength

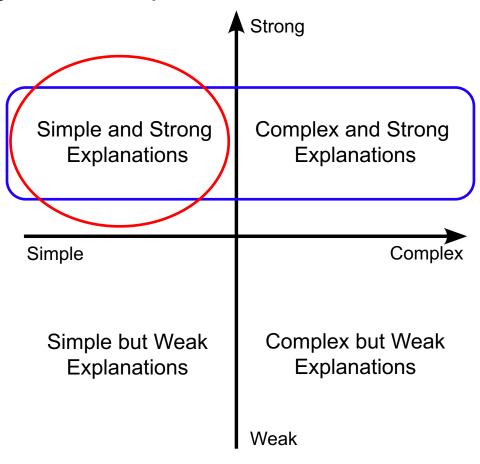
Two orthogonal concepts





Complexity vs. Strength

Two orthogonal concepts





Counterfactual Learning and Reasoning

Seek simple and effective explanations

minimize Explanation Complexity s.t., Explanation is Strong Enough $S_{c}(M_{k}, F_{k}) > P_{\Phi}(\hat{y}_{k,s}) | A_{k} \odot M_{k}, X_{k} \odot F_{k}),$ $S_{c}(M_{k}, F_{k}) > -P_{\Phi}(\hat{y}_{k,s}) | A_{k} - A_{k} \odot M_{k}, X_{k} - X_{k} \odot F_{k})$

- $\hat{y}_{k,s}$ is the label of the second largest prediction probability
- Idea: Find minimal components of a molecule which is both sufficient and necessary
- Relaxed Optimization based on Lagrange Multiplier for model learning

minimize
$$||M_{k}^{*}||_{1} + ||F_{k}^{*}||_{1} + \lambda(\alpha L_{f} + (1 - \alpha)L_{c})$$

$$L_{f} = \text{ReLU}(\gamma + P_{\Phi}(\hat{y}_{k,s} \mid A_{k} \odot M_{k}^{*}, X_{k} \odot F_{k}^{*}) \quad L_{c} = \text{ReLU}(\gamma - S_{c}(M_{k}^{*}, F_{k}^{*}) \\ -S_{f}(M_{k}^{*}, F_{k}^{*})) \quad -P_{\Phi}(\hat{y}_{k,s} \mid A_{k} - A_{k} \odot M_{k}^{*}, X_{k} - X_{k} \odot F_{k}^{*}))$$



Counterfactual Learning and Reasoning

Seek simple and effective explanations

minimize Explanation Complexity s.t., Explanation is Strong Enough $Sc(M_k, F_k) > P_{\Phi}(\hat{y}_{k,s}) | A_k \odot M_k, X_k \odot F_k),$

- $\hat{y}_{k,s}$ is the label of the second largest prediction probability
- Idea: Find minimal components of a molecule which is both sufficient and necessary

Objectives	Simple (Complexity)	Effective (Strength)		
Measure	#edges, #features	Sufficiency	Necessity	
Method	Minimization	Factual	Counterfactual	



Sufficiency and Necessity of Explanations

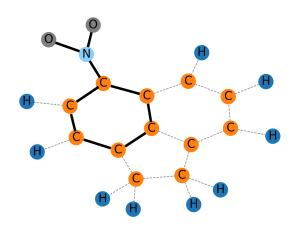
- S ⇒ N: S is a sufficient condition for N
- ¬N ⇒ ¬S: N is a necessary condition for S



Sufficiency and Necessity of Explanations

- S ⇒ N: S is a sufficient condition for N
- ¬N ⇒ ¬S: N is a necessary condition for S
- Probability of Sufficient (PS): If we only keep the nodes/edges in the explanation, the
 prediction result will be the same, then we say the explanation is sufficient
- PS: percentage of molecules whose explanation sub-graph is sufficient

$$PS = \frac{\sum_{G_k \in \mathcal{G}} ps_k}{|\mathcal{G}|}, \text{ where } ps_k = \begin{cases} 1, \text{ if } \hat{y}_k' = \hat{y}_k \\ 0, \text{ else} \end{cases}$$
where $\hat{y}_k' = \underset{c \in \mathcal{C}}{\arg \max} P_{\Phi}(c \mid A_k \odot M_k, X_k \odot F_k)$





Sufficiency and Necessity of Explanations

- S ⇒ N: S is a sufficient condition for N
- ¬N ⇒ ¬S: N is a necessary condition for S
- Probability of Necessity (PN): If we remove the nodes/edges in the explanation, the
 prediction result will change, then we say the explanation is necessary
- PN: percentage of molecules whose explanation sub-graph is necessary

$$\operatorname{PN} = \frac{\sum_{G_k \in \mathcal{G}} \operatorname{pn}_k}{|\mathcal{G}|}, \text{ where } \operatorname{pn}_k = \begin{cases} 1, & \text{if } \hat{y}_k' \neq \hat{y}_k \\ 0, & \text{else} \end{cases}$$
 where $\hat{y}_k' = \underset{c \in C}{\operatorname{arg max}} P_{\Phi}(c \mid A_k - A_k \odot M_k, X_k - X_k \odot F_k)$



Datasets for Evaluation

Dataset	#graph	#ave n	#ave e	#class	#feat	task	gt
BA-Shapes	1	700	4100	4	-	node	✓
Tree-Cycles	1	871	1950	2	_	node	✓
Mutag	4337	30.32	30.77	2	14	graph	
$Mutag_0$	2301	31.74	32.54	2	14	graph	✓
NCI1	4110	29.87	32.30	2	37	graph	
CiteSeer	1	3312	4732	6	3703	node	



Evaluate Explanation Quality with PN, PS

(without ground-truth explanation)

Models	BA-Shapes			Tree-Cycles			\mathbf{Mutag}_0					
	PN%	PS%	F _{NS} %	#exp	PN%	PS%	F _{NS} %	#exp	PN%	PS%	F _{NS} %	#exp
GNNExplainer [†]	72.19	45.62	55.91	6.00	100.00	59.72	74.78	6.00	71.79	97.44	82.67	15.00
CF-GNNExplainer	75.34	41.10	53.18	5.79	100.00	31.94	48.42	3.44	96.26	7.48	13.88	7.72
Gem [†]	61.36	52.27	56.45	6.00	100.00	29.89	46.02	6.00	83.01	76.42	79.58	15.00
CF^2	76.73	68.22	72.07	6.21	100.00	81.94	90.08	5.81	97.44	100.00	98.70	14.95
Models	NCI1				CiteSeer (edge)			CiteSeer (feature)				
Wiodels	PN%	PS%	F _{NS} %	#exp	PN%	PS%	F _{NS} %	#exp	PN%	PS%	F _{NS} %	#exp
GNNExplainer [†]	92.13	62.16	74.24	15.00	66.67	90.05	76.61	5.00	71.64	99.50	72.79	60.00
CF-GNNExplainer	97.14	31.43	47.49	7.75	69.50	82.00	75.23	2.58	72.14	92.54	81.07	72.91
Gem [†]	99.03	52.15	68.32	15.00	61.05	72.67	66.36	5.00	-	-	-	-
CF ²	<u>100.00</u>	<u>63.81</u>	77.91	17.70	<u>71.00</u>	<u>94.50</u>	81.08	3.18	<u>74.63</u>	95.02	83.60	62.73



Evaluate Explanation Quality with Accuracy

(with ground-truth explanation)

Models	BA-Shapes			Tree-Cycles			Mutag ₀					
	Acc%	Pr%	Re%	F ₁ %	Acc%	Pr%	Re%	F ₁ %	Acc%	Pr%	Re%	F ₁ %
GNNExplainer [†]	95.25	60.08	60.08	60.08	92.78	68.06	68.06	68.06	96.96	59.71	85.17	68.85
CF-GNNExplainer	94.39	67.19	54.11	56.79	90.27	<u>87.40</u>	47.45	59.10	96.91	66.09	39.46	47.39
Gem [†]	96.97	64.16	64.16	64.16	89.88	57.23	57.23	57.23	96.43	63.12	47.11	54.68
$\mathbb{C}\mathbb{F}^2$	96.37	73.15	<u>68.18</u>	66.61	93.26	84.92	<u>73.84</u>	75.69	97.34	65.28	88.59	72.56

Kendall's τ and Spearman's ρ correlation scores

Models	BA-S	hapes	Tree-	Cycles	$Mutag_0$		
	$\tau \uparrow$	$\rho\uparrow$	$\tau \uparrow$	$\rho\uparrow$	$\tau \uparrow$	$\rho\uparrow$	
F _{NS} & F ₁	1.00	1.00	1.00	1.00	1.00	1.00	
F _{NS} & Acc	0.66	0.79	1.00	1.00	0.66	0.79	

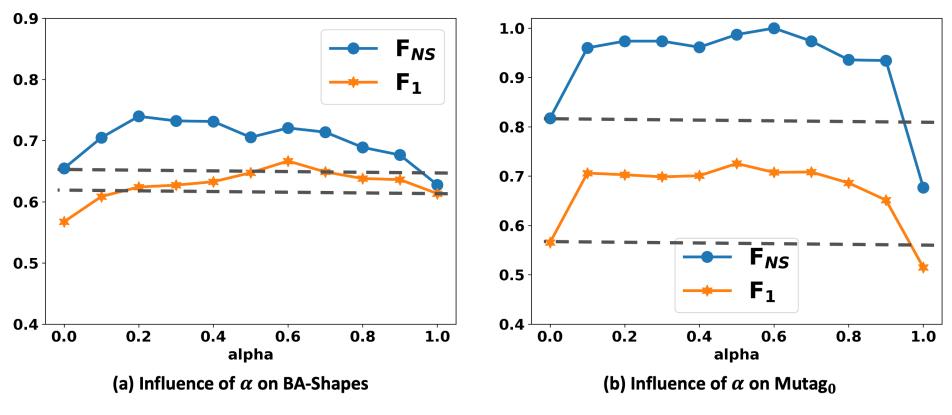
$$F_{NS} = \frac{2PN \cdot PS}{PN + PS}$$

PN/PS-based evaluation is highly consistent with ground-truth-based evaluation. We can use PN/PS to evaluate explanations when ground-truth is not available



Factual vs. Counterfactual Explanations

minimize
$$||M_k^*||_1 + ||F_k^*||_1 + \lambda(\alpha L_f + (1 - \alpha)L_c)$$



Both factual and counterfactual reasoning are important



- Task: Predict if a species is endangered or not [15]
 - An important nature-oriented task
 - A dynamic task: species that were not endangered may become endangered now, and vice versa
 - Needs dynamic monitoring and fast reaction
 - E.g., IUCN Red List maintains the status for animal species
 - Critically Endangered, Endangered, Extinct, Extinct in the Wild, Least Concern, Low Risk, Threatened, Vulnerable



From the IUCN (International Union for Conservation of Nature) Red List of Threatened Species https://www.iucnredlist.org

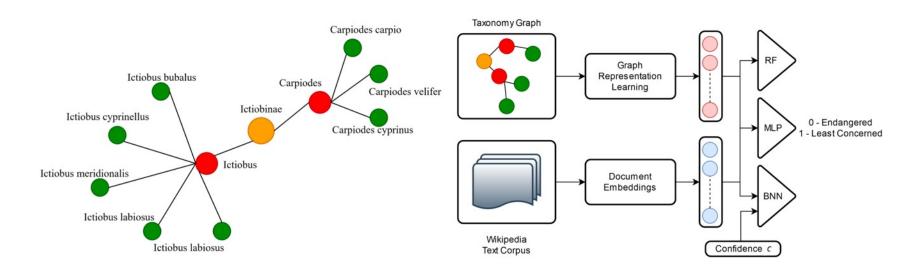


- Machine learning may help as an assistive tool
 - Why Machine Learning may work?
 - Intuition: Species become endangered mostly because habitat destruction due to human activities
 - If we know one species in a habitat is endangered, other species in the same habitat may too
- Habitat (and other useful information) can be found in Wikipedia
 - Information is dynamic/up-to-date due to real-time edits





- Wikipedia text is not enough
 - Due to Interspecific Competition, one species get endangered may imply another competitor species get more populated
- Solution: Graph-Text Co-Learning for Animal Biodiversity Conservation [15]
 - Animal taxonomy graph shows the relationship between species





Metric	Value	Model	F1 Score -A	AUC
Total animal species	45,170	RF w/ node2vec	0.862 0	784
Endangered animal species	10,947	0.000		
Least-concern animal species	27,053	RF w/ doc2vec	0.869 0).820
Data-Deficient species	7,170	RF w/ node2vec + doc2vec	0.860 0).827
Average length of Wikipedia documents	146	MLP w/ node2vec	0.843 0	729
in training corpus (number of words)				
Documents with length more than average length	13,970	MLP w/ doc2vec	0.886 0).864
Documents with length less than average length	31,200	MLP w/ node2vec + doc2vec	0.885 0).873
Documents that explicitly contain Red List status information	14,253	BNN w/ node2vec + doc2vec + $c \ge 0.75$	0.856 0	1868
BNN training data points	14,083			
BNN test data points ($c \ge 0.75$)	3,521	BNN w/ node2vec + doc2vec + $c \ge 0.9$	0.889 0).911

Dataset statistics (data collected from Wikipedia, IUCN, and ITIS)

Prediction accuracy

Nycticryphes semicollaris - The South American painted-snipe (Nycticryphes semicollaris), or lesser painted-snipe, is a shorebird in the family Rostratulidae. There are two other species in its family, the Australian painted-snipe and the greater painted-snipe. Measurements: 19–23 cm in length; 65–86 g in weight. Vocalizations: A hoarse, hissing "wee-oo" has been recorded from birds in captivity. Distribution and habitat: The species is found in the southern third of South America, from southern Brazil, Paraguay, and Uruguay to Chile and Argentina. It inhabits lowland freshwater wetlands, including wet grasslands. Breeding: South American painted-snipes are monogamous and breed semi-colonially. The nest is a shallow cup on the ground in a wetland, with a clutch of 2-3 eggs. Breeding has been recorded mainly from July to February. Feeding: The South American painted-snipe is omnivorous, feeding by probing in mud and shallow water for small animals and seeds, often at dusk.



Attention-based Explanation

RUTGERS

Summary

- Rediscover Kepler's laws and Newton's laws from Tycho's ancient data [1]
 - A good example to demonstrate the idea of XAI-driven scientific research
 - Pay our respect to some of the greatest minds in human history
- More "practical" Examples
 - Explainable AI for Molecular Property Prediction [2]
 - Explainable AI for Biodiversity Conservation [3]
- [1] Zelong Li, Jianchao Ji, and Yongfeng Zhang. "From Kepler to Newton: Explainable AI for Science Discovery." In ICML AI for Science 2022.
- [2] Juntao Tan, Shijie Geng, Zuohui Fu, Yingqiang Ge, Shuyuan Xu, Yunqi Li, and Yongfeng Zhang. "Learning and evaluating graph neural network explanations based on counterfactual and factual reasoning." In Proceedings of the ACM Web Conference 2022.
- [3] Meet Mukadam, Mandhara Jayaram, and Yongfeng Zhang. "A Representation Learning Approach to Animal Biodiversity Conservation." In Proceedings of the 28th International Conference on Computational Linguistics. 2020.



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